Efficient Construction of Flows for the One-Way Measurement Model

Niel de Beaudrap



Institute for Quantum Computing University of Waterloo



CQISC 2006, Calgary

Efficient Construction of Flows

CQISC 2006 1 / 20



Introduction

- The One-Way Measurement Model
- Flows in one-way patterns
- 2 Phase Map Decompositions

3 Graph-theoretic results

- Path covers
- Influencing walks, Vicious circuits
- Uniqueness when |I| = |O|

4) Efficient algorithms when |I| = |O|



Introduction

- The One-Way Measurement Model
- Flows in one-way patterns

Phase Map Decompositions

3 Graph-theoretic results

- Path covers
- Influencing walks, Vicious circuits
- Uniqueness when |I| = |O|

4) Efficient algorithms when |I| = |O|



Introduction

- The One-Way Measurement Model
- Flows in one-way patterns
- 2 Phase Map Decompositions

Graph-theoretic results

- Path covers
- Influencing walks, Vicious circuits
- Uniqueness when |I| = |O|

4) Efficient algorithms when |I| = |O|



Introduction

- The One-Way Measurement Model
- Flows in one-way patterns
- 2 Phase Map Decompositions

Graph-theoretic results

- Path covers
- Influencing walks, Vicious circuits
- Uniqueness when |I| = |O|





Introduction

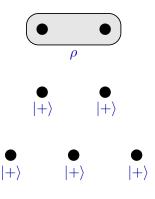
- The One-Way Measurement Model
- Flows in one-way patterns
- 2 Phase Map Decompositions

3 Graph-theoretic results

- Path covers
- Influencing walks, Vicious circuits
- Uniqueness when |I| = |O|

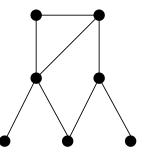


- Prepare a state ρ to be transformed in an input system *I*, and a collection of ancillas in the |+> state;
- act on the ancillas and the qubits of I using controlled-Z operators to form an entanglement graph G;
- perform a sequence of single-qubit measurements on the qubits of *G*, leaving only an output system *O*;
- erform Pauli corrections on O, yielding the output state.



제 글 에 제 글 에 크 글 글

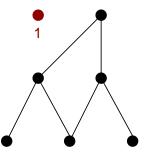
- Prepare a state ρ to be transformed in an input system *I*, and a collection of ancillas in the |+> state;
- act on the ancillas and the qubits of I using controlled-Z operators to form an entanglement graph G;
- perform a sequence of single-qubit measurements on the qubits of G, leaving only an output system O;
- perform Pauli corrections on O, yielding the output state.



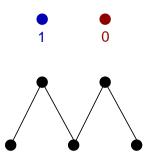
김 글 제 김 권 제 크네크

- Prepare a state ρ to be transformed in an input system *I*, and a collection of ancillas in the |+> state;
- act on the ancillas and the qubits of I using controlled-Z operators to form an entanglement graph G;
- perform a sequence of single-qubit measurements on the qubits of G, leaving only an output system O;

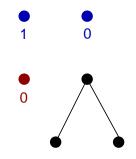




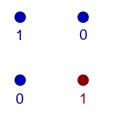
- Prepare a state ρ to be transformed in an input system *I*, and a collection of ancillas in the |+> state;
- act on the ancillas and the qubits of I using controlled-Z operators to form an entanglement graph G;
- perform a sequence of single-qubit measurements on the qubits of G, leaving only an output system O;
- erform Pauli corrections on O, yielding the output state.



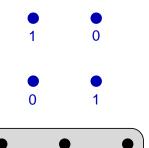
- Prepare a state ρ to be transformed in an input system *I*, and a collection of ancillas in the |+> state;
- act on the ancillas and the qubits of I using controlled-Z operators to form an entanglement graph G;
- perform a sequence of single-qubit measurements on the qubits of G, leaving only an output system O;
- perform Pauli corrections on O, yielding the output state.



- Prepare a state ρ to be transformed in an input system *I*, and a collection of ancillas in the |+> state;
- act on the ancillas and the qubits of I using controlled-Z operators to form an entanglement graph G;
- perform a sequence of single-qubit measurements on the qubits of G, leaving only an output system O;
- perform Pauli corrections on O, yielding the output state.

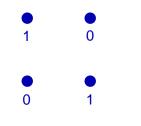


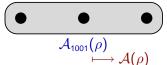
- Prepare a state ρ to be transformed in an input system *I*, and a collection of ancillas in the |+> state;
- act on the ancillas and the qubits of I using controlled-Z operators to form an entanglement graph G;
- perform a sequence of single-qubit measurements on the qubits of G, leaving only an output system O;
- perform Pauli corrections on O, yielding the output state.



 $\mathcal{A}_{1001}(\rho)$

- Prepare a state ρ to be transformed in an input system *I*, and a collection of ancillas in the |+> state;
- act on the ancillas and the qubits of I using controlled-Z operators to form an entanglement graph G;
- perform a sequence of single-qubit measurements on the qubits of G, leaving only an output system O;
- 9 perform Pauli corrections on O, yielding the output state.





The One-Way Measurement Model

 Each qubit x ∉ O is measured with some operator on the equator of the Bloch sphere, determined by a measurement angle α_x

$$\begin{aligned} M_{\alpha} &= |+_{\alpha}\rangle\langle +_{\alpha}| - |-_{\alpha}\rangle\langle -_{\alpha}| & |+_{\alpha}\rangle &\longmapsto 0 \\ |\pm_{\alpha}\rangle &= \frac{1}{\sqrt{2}}\left(|0\rangle \pm e^{i\alpha}|1\rangle\right) & |-_{\alpha}\rangle &\longmapsto 1 \end{aligned}$$

• Measurements may (and almost always do) depend on the results $s_x \in \{0, 1\}$ of previous measurements

e.g.
$$\alpha_z \longmapsto (-1)^{s_x+s_y} \alpha_z$$

 Dependencies arise from how information is propagated through the entanglement graph
 ⇒ the graph restricts the order of measurements

The One-Way Measurement Model

 Each qubit x ∉ O is measured with some operator on the equator of the Bloch sphere, determined by a measurement angle α_x

• Measurements may (and almost always do) depend on the results $s_x \in \{0, 1\}$ of previous measurements

e.g.
$$\alpha_z \longmapsto (-1)^{s_x+s_y} \alpha_z$$

 Dependencies arise from how information is propagated through the entanglement graph
 ⇒ the graph restricts the order of measurements

The One-Way Measurement Model

 Each qubit x ∉ O is measured with some operator on the equator of the Bloch sphere, determined by a measurement angle α_x

• Measurements may (and almost always do) depend on the results $s_x \in \{0, 1\}$ of previous measurements

e.g.
$$\alpha_z \longmapsto (-1)^{s_x+s_y} \alpha_z$$

- Dependencies arise from how information is propagated through the entanglement graph
 the graph restricts the order of measurements
 - \Rightarrow the graph restricts the order of measurements

[Danos, Kashefi 2005]

Flows describe how information is "transmitted" in an entanglement graph G = (V, E), from the inputs $I \subseteq V$ to the outputs $O \subseteq V$.

Definition

A flow on (G, I, O) is an ordered pair (f, \preccurlyeq)

- $f: O^{c} \longrightarrow I^{c}$ is a function on vertices
- \preccurlyeq is a partial order on V

(i.e. a reflexive, transitive, & antisymmetric relation)

which satisfy the following three conditions for all vertices:

(Fi)
$$x \sim f(x)$$
;
(Fii) $x \preccurlyeq f(x)$;
(Fiii) $y \sim f(x) \Rightarrow x \preccurlyeq y$.

[Danos, Kashefi 2005]

Flows describe how information is "transmitted" in an entanglement graph G = (V, E), from the inputs $I \subseteq V$ to the outputs $O \subseteq V$.

Definition

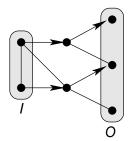
A flow on (G, I, O) is an ordered pair (f, \preccurlyeq)

- $f: O^{c} \longrightarrow I^{c}$ is a function on vertices
- \preccurlyeq is a partial order on V

(i.e. a reflexive, transitive, & antisymmetric relation)

which satisfy the following three conditions for all vertices:

(Fi) $x \sim f(x)$; (Fii) $x \preccurlyeq f(x)$; (Fiii) $y \sim f(x) \Rightarrow x \preccurlyeq y$.



[Danos, Kashefi 2005]

Flows describe how information is "transmitted" in an entanglement graph G = (V, E), from the inputs $I \subseteq V$ to the outputs $O \subseteq V$.

Definition

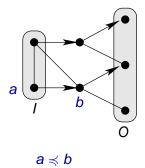
A flow on (G, I, O) is an ordered pair (f, \preccurlyeq)

- $f: O^{c} \longrightarrow I^{c}$ is a function on vertices
- \preccurlyeq is a partial order on V

(i.e. a reflexive, transitive, & antisymmetric relation)

which satisfy the following three conditions for all vertices:

(Fi) $x \sim f(x)$; (Fii) $x \preccurlyeq f(x)$; (Fiii) $y \sim f(x) \Rightarrow x \preccurlyeq y$.



<<p>(日本)

[Danos, Kashefi 2005]

Flows describe how information is "transmitted" in an entanglement graph G = (V, E), from the inputs $I \subseteq V$ to the outputs $O \subseteq V$.

Definition

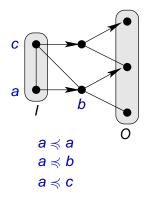
A flow on (G, I, O) is an ordered pair (f, \preccurlyeq)

- $f: O^{c} \longrightarrow I^{c}$ is a function on vertices
- \preccurlyeq is a partial order on V

(i.e. a reflexive, transitive, & antisymmetric relation)

which satisfy the following three conditions for all vertices:

(Fi)
$$x \sim f(x)$$
;
(Fii) $x \preccurlyeq f(x)$;
(Fiii) $y \sim f(x) \Rightarrow x \preccurlyeq y$.



[Danos, Kashefi 2005]

Flows describe how information is "transmitted" in an entanglement graph G = (V, E), from the inputs $I \subseteq V$ to the outputs $O \subseteq V$.

Definition

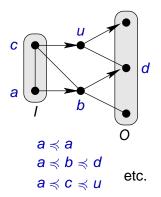
A flow on (G, I, O) is an ordered pair (f, \preccurlyeq)

- $f: O^{c} \longrightarrow I^{c}$ is a function on vertices
- \preccurlyeq is a partial order on V

(i.e. a reflexive, transitive, & antisymmetric relation)

which satisfy the following three conditions for all vertices:

(Fi)
$$x \sim f(x)$$
;
(Fii) $x \preccurlyeq f(x)$;
(Fiii) $y \sim f(x) \Rightarrow x \preccurlyeq y$.



周天 시골 지수 물 지 모님.

[Danos, Kashefi 2005]

The existence of a flow is an entirely graph-theoretic property, but guarantees properties important for quantum computation:

- For any choice of measurement angles {α_ν}_{ν∈O^c}, there is a one-way pattern with a measurement order consistent with ≼, which performs a unitary injection;
- In that pattern, the result of each measurement is uniformly random.
- Also: every unitary operator can be implemented by a one-way pattern whose measurement order is described by a flow.

This makes them a potentially useful tool for analysing:

[Danos, Kashefi 2005]

The existence of a flow is an entirely graph-theoretic property, but guarantees properties important for quantum computation:

- For any choice of measurement angles {α_ν}_{ν∈O^c}, there is a one-way pattern with a measurement order consistent with ≼, which performs a unitary injection;
- In that pattern, the result of each measurement is uniformly random.
- Also: every unitary operator can be implemented by a one-way pattern whose measurement order is described by a flow.

This makes them a potentially useful tool for analysing:

[Danos, Kashefi 2005]

The existence of a flow is an entirely graph-theoretic property, but guarantees properties important for quantum computation:

- For any choice of measurement angles {α_ν}_{ν∈O^c}, there is a one-way pattern with a measurement order consistent with ≼, which performs a unitary injection;
- In that pattern, the result of each measurement is uniformly random.
- Also: every unitary operator can be implemented by a one-way pattern whose measurement order is described by a flow.

This makes them a potentially useful tool for analysing:

▲□▶ ▲掃▶ ▲ヨ▶ ▲ヨ▶ ヨヨ めのゆ



- The One-Way Measurement Model ۲

Phase Map Decompositions

- Path covers
- Influencing walks, Vicious circuits ۲



Consider a one-way pattern implementing a unitary operator U:

- entanglement graph G = (V, E), input/output vertices $I, O \subseteq V$, such that (G, I, O) has a flow
- measurement angles $\{\alpha_{v}\}_{v \in O^{c}}$

Considering U, between standard bases of \mathcal{H}_{I} and \mathcal{H}_{O} :

$$U_{I
ightarrow 0} = R_{V
ightarrow 0} \circ \Phi_G \circ P_{I
ightarrow V} \; ,$$

• *P* : a *preparation map*, setting all qubits in *I*^c in the state $|+\rangle$

- *R* : a *restriction map*, post-selecting $|+\rangle$ for all qubits in O^c
- Φ_G : a diagonal unitary operator (or *phase map*) with the structure

$$\Phi_G = \left[\bigotimes_{v \in O^c} e^{-i\alpha_v |1\rangle\langle 1|_v}\right] \left[\prod_{uv \in E} \wedge Z_{u,v}\right]$$

Consider a one-way pattern implementing a unitary operator U:

- entanglement graph G = (V, E), input/output vertices $I, O \subseteq V$, such that (G, I, O) has a flow
- measurement angles $\{\alpha_{v}\}_{v \in O^{c}}$

Considering U, between standard bases of \mathcal{H}_I and \mathcal{H}_O :

$$U_{I
ightarrow 0}$$
 = $R_{V
ightarrow 0}$ \circ Φ_{G} \circ $P_{I
ightarrow V}$,

- **P**: a preparation map, setting all qubits in I^{c} in the state $|+\rangle$
- **R**: a restriction map, post-selecting $|+\rangle$ for all qubits in O^{c}
- Φ_G : a diagonal unitary operator (or *phase map*) with the structure

$$\Phi_G = \left[\bigotimes_{v \in O^c} e^{-i\alpha_v |1\rangle\langle 1|_v}\right] \left[\prod_{uv \in E} \wedge Z_{u,v}\right]$$

Consider a one-way pattern implementing a unitary operator U:

- entanglement graph G = (V, E), input/output vertices $I, O \subseteq V$, such that (G, I, O) has a flow
- measurement angles $\{\alpha_{v}\}_{v \in O^{c}}$

Considering U, between standard bases of \mathcal{H}_{I} and \mathcal{H}_{O} :

$$U_{I
ightarrow 0} = R_{V
ightarrow 0} \circ \Phi_G \circ P_{I
ightarrow V} \; ,$$

- **P**: a preparation map, setting all qubits in I^{c} in the state $|+\rangle$
- **R**: a restriction map, post-selecting $|+\rangle$ for all qubits in O^{c}
- Φ_G: a diagonal unitary operator (or phase map) with the structure

$$\Phi_{G} = \left[\bigotimes_{v \in O^{c}} e^{-i\alpha_{v}|1\rangle\langle 1|_{v}}\right] \left[\prod_{uv \in E} \wedge Z_{u,v}\right]$$

[B, Danos, Kashefi 2006]

$$U_{I
ightarrow 0} = R_{V
ightarrow 0} \circ \Phi_G \circ P_{I
ightarrow V} \; ,$$

- **P**: a preparation map, setting all qubits in I^c in the state $|+\rangle$
- **R**: a restriction map, post-selecting $|+\rangle$ for all qubits in O^{c}
- Φ_G: a diagonal unitary operator (or phase map) with the structure

$$\Phi_{G} = \left[\bigotimes_{v \in O^{c}} e^{-i\alpha_{v}|1\rangle\langle 1|_{v}}\right] \left[\prod_{uv \in E} \wedge Z_{u,v}\right]$$

[B, Danos, Kashefi 2006]



$$U_{I
ightarrow 0} = R_{V
ightarrow 0} \circ \Phi_G \circ P_{I
ightarrow V} \; ,$$

- **P**: a preparation map, setting all qubits in I^{c} in the state $|+\rangle$
- **R**: a restriction map, post-selecting $|+\rangle$ for all qubits in O^{c}
- Φ_G: a diagonal unitary operator (or phase map) with the structure

$$\Phi_{G} = \left[\bigotimes_{v \in O^{c}} e^{-i\alpha_{v}|1\rangle\langle 1|_{v}}\right] \left[\prod_{uv \in E} \wedge Z_{u,v}\right]$$

[B, Danos, Kashefi 2006]

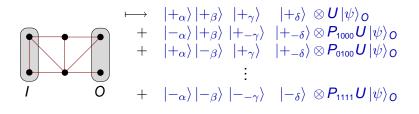


$$U_{I
ightarrow 0} = R_{V
ightarrow 0} \circ \Phi_G \circ P_{I
ightarrow V}$$
 ,

- **P**: a preparation map, setting all qubits in I^{c} in the state $|+\rangle$
- **R**: a restriction map, post-selecting $|+\rangle$ for all qubits in O^{c}
- Φ_G: a diagonal unitary operator (or phase map) with the structure

$$\Phi_{G} = \left[\bigotimes_{v \in O^{c}} e^{-i\alpha_{v}|1\rangle\langle 1|_{v}}\right] \left[\prod_{uv \in E} \wedge Z_{u,v}\right]$$

[B, Danos, Kashefi 2006]

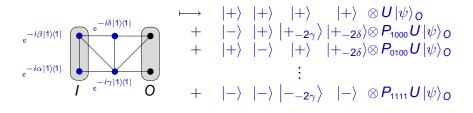


$$U_{I
ightarrow 0} = R_{V
ightarrow 0} \circ \Phi_{\mathsf{G}} \circ P_{I
ightarrow V} \; ,$$

- *P* : a *preparation map*, setting all qubits in *I*^c in the state $|+\rangle$
- **R**: a restriction map, post-selecting $|+\rangle$ for all qubits in O^{c}
- Φ_G: a diagonal unitary operator (or phase map) with the structure

$$\Phi_{G} = \left[\bigotimes_{\mathbf{v}\in O^{c}} e^{-i\alpha_{\mathbf{v}}|\mathbf{1}\backslash\mathbf{1}|_{\mathbf{v}}}\right] \left[\prod_{\mathbf{u}\mathbf{v}\in E} \wedge Z_{\mathbf{u},\mathbf{v}}\right]$$

[B, Danos, Kashefi 2006]



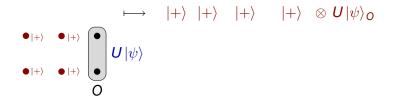
$$U_{I \to 0} = R_{V \to 0} \circ \Phi_{\mathbf{G}} \circ P_{I \to V} ,$$

- **P**: a preparation map, setting all qubits in I^{c} in the state $|+\rangle$
- **R**: a restriction map, post-selecting $|+\rangle$ for all qubits in O^{c}
- Φ_G: a diagonal unitary operator (or phase map) with the structure

$$\Phi_{G} = \left[\bigotimes_{v \in O^{c}} e^{-i\alpha_{v}|1\rangle\langle 1|_{v}}\right] \left[\prod_{uv \in E} \wedge Z_{u,v}\right]$$

같은 가 같은 것같이요.

[B, Danos, Kashefi 2006]



$$U_{I \to 0} \quad = \quad R_{V \to 0} \circ \Phi_{G} \circ P_{I \to V} \ ,$$

- **P**: a preparation map, setting all qubits in I^{c} in the state $|+\rangle$
- **R**: a restriction map, post-selecting $|+\rangle$ for all qubits in O^{c}
- Φ_G: a diagonal unitary operator (or phase map) with the structure

$$\Phi_{G} = \left[\bigotimes_{v \in O^{c}} e^{-i\alpha_{v}|1\rangle\langle 1|_{v}}\right] \left[\prod_{uv \in E} \wedge Z_{u,v}\right]$$

- Phase Map Decompositions describe how one-way measurement patterns evolve in one special case. So, if we can find:
 - Φ_{G} realising a phase map decomposition for $U_{I \rightarrow O}$
 - a flow for (G, I, O)

then we can obtain a one-way pattern for U.

Phase Map Decomposition

- Phase Map Decompositions describe how one-way measurement patterns evolve in one special case. So, if we can find:
 - Φ_{G} realising a phase map decomposition for $U_{I \rightarrow O}$
 - a flow for (G, I, O)

then we can obtain a one-way pattern for U.

For which families of unitary operators *U* can we efficiently find phase map decompositions?

Phase Map Decomposition

- Phase Map Decompositions describe how one-way measurement patterns evolve in one special case. So, if we can find:
 - Φ_{G} realising a phase map decomposition for $U_{I \rightarrow O}$
 - a flow for (G, I, O)

then we can obtain a one-way pattern for U.

For which families of unitary operators *U* can we efficiently find phase map decompositions?

• Candidate sub-problem: given (*G*, *I*, *O*), determine whether it has a flow (and find one if it does).

Outline



- The One-Way Measurement Model
- Flows in one-way patterns
- Phase Map Decompositions

Graph-theoretic results

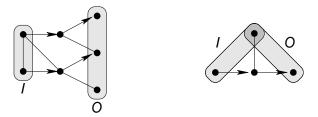
- Path covers
- Influencing walks, Vicious circuits
- Uniqueness when |I| = |O|



-

The Sec. 74

Flows describe "Path covers"



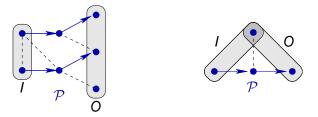
Paths taken by following edges $x \rightarrow f(x)$:

- inputs can only be at the beginning of paths, outputs at the end
- for distinct $x, y \in O^c$, we have $f(x) \neq f(y)$
- ⇒ f describes a set \mathcal{P} of non-intersecting paths* in G, ending in O. Call this a *path cover* for (G, I, O).

(* paths not guaranteed to have non-zero length)

• If |I| = |O|, then \mathcal{P} is a collection of paths from *I* to *O*.

Flows describe "Path covers"



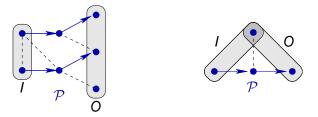
Paths taken by following edges $x \rightarrow f(x)$:

- inputs can only be at the beginning of paths, outputs at the end
- for distinct $x, y \in O^c$, we have $f(x) \neq f(y)$
- ⇒ *f* describes a set \mathcal{P} of non-intersecting paths* in *G*, ending in *O*. Call this a *path cover* for (*G*, *I*, *O*).

(* paths not guaranteed to have non-zero length)

• If |I| = |O|, then \mathcal{P} is a collection of paths from *I* to *O*.

Flows describe "Path covers"

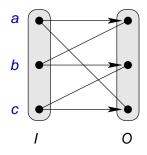


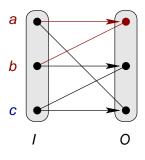
Paths taken by following edges $x \rightarrow f(x)$:

- inputs can only be at the beginning of paths, outputs at the end
- for distinct $x, y \in O^c$, we have $f(x) \neq f(y)$
- ⇒ *f* describes a set \mathcal{P} of non-intersecting paths* in *G*, ending in *O*. Call this a *path cover* for (*G*, *I*, *O*).

(* paths not guaranteed to have non-zero length)

• If |I| = |O|, then \mathcal{P} is a collection of paths from I to O.



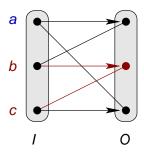


 $b \sim f(a) \Rightarrow a \preccurlyeq b$

Niel de Beaudrap (IQC, UW)

Efficient Construction of Flows

CQISC 2006 13 / 20

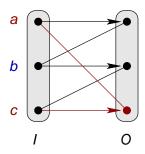


 $b \sim f(a) \Rightarrow a \preccurlyeq b$ $c \sim f(b) \Rightarrow b \preccurlyeq c$

Niel de Beaudrap (IQC, UW)

Efficient Construction of Flows

CQISC 2006 13 / 20



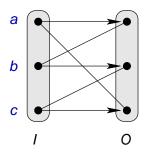
$$b \sim f(a) \Rightarrow a \preccurlyeq b$$

 $c \sim f(b) \Rightarrow b \preccurlyeq c$
 $a \sim f(c) \Rightarrow c \preccurlyeq a$

Niel de Beaudrap (IQC, UW)

Efficient Construction of Flows

CQISC 2006 13 / 20



$$b \sim f(a) \Rightarrow a \preccurlyeq b$$

 $c \sim f(b) \Rightarrow b \preccurlyeq c$
 $a \sim f(c) \Rightarrow c \preccurlyeq a$

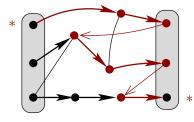
$a \preccurlyeq b \preccurlyeq c \preccurlyeq a$

Influencing walks, Vicious circuits

Definition

An **influencing walk** of a path-cover \mathcal{P} is a directed walk in G which can be decomposed into paths of the following two types (using arcs of \mathcal{P}):

- a single arc, $x \to y$;
- \bigcirc a single arc $x \rightarrow y$, followed by any edge $yz \in E$



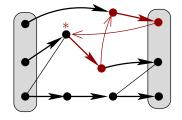
Influencing walks, Vicious circuits

Definition

An **influencing walk** of a path-cover \mathcal{P} is a directed walk in G which can be decomposed into paths of the following two types (using arcs of \mathcal{P}):

- a single arc, $x \to y$;
- a single arc $x \to y$, followed by any edge $yz \in E$

A **vicious circuit** is an influencing walk which starts and ends at the same vertex.



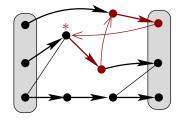
Influencing walks, Vicious circuits

Definition

An **influencing walk** of a path-cover \mathcal{P} is a directed walk in G which can be decomposed into paths of the following two types (using arcs of \mathcal{P}):

- a single arc, $x \to y$;
- a single arc $x \to y$, followed by any edge $yz \in E$

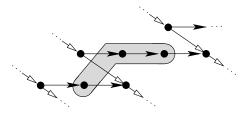
A **vicious circuit** is an influencing walk which starts and ends at the same vertex.



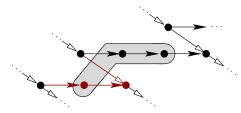
Theorem:

a geometry (G, I, O) has a flow iff it has a path cover with no vicious circuits.

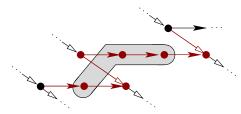
- \mathcal{P} a path cover (solid arrows)
- \mathcal{F} a (different) collection of I O paths (hollow arrows), with the same number of paths
- shaded area: vertices not covered by \mathcal{F}



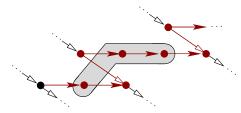
- \mathcal{P} a path cover (solid arrows)
- \mathcal{F} a (different) collection of I O paths (hollow arrows), with the same number of paths
- shaded area: vertices not covered by \mathcal{F}



- \mathcal{P} a path cover (solid arrows)
- \mathcal{F} a (different) collection of I O paths (hollow arrows), with the same number of paths
- shaded area: vertices not covered by ${\cal F}$

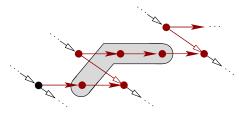


- \mathcal{P} a path cover (solid arrows)
- \mathcal{F} a (different) collection of I O paths (hollow arrows), with the same number of paths
- shaded area: vertices not covered by ${\cal F}$



A B A A B A B

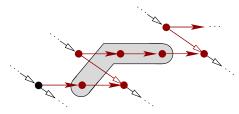
- \mathcal{P} a path cover (solid arrows)
- \mathcal{F} a (different) collection of I O paths (hollow arrows), with the same number of paths
- shaded area: vertices not covered by *F*



⇒ we can construct an infinitely long influencing walk — which will eventually close up into a vicious circuit.

김 권 씨가 전 씨는 전 문 문

- \mathcal{P} a path cover (solid arrows)
- \mathcal{F} a (different) collection of I O paths (hollow arrows), with the same number of paths
- shaded area: vertices not covered by *F*



Theorem:

if |I| = |O| and (G, I, O) has a path cover \mathcal{P} without vicious circuits, then \mathcal{P} is the only maximum-size collection of disjoint I - O paths.

Outline



- The One-Way Measurement Model
- Flows in one-way patterns
- 2 Phase Map Decompositions

3) Graph-theoretic results

- Path covers
- Influencing walks, Vicious circuits
- Uniqueness when |I| = |O|

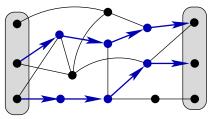
Efficient algorithms when |I| = |O|

-

4 3 5 4 3

If (G, I, O) has a flow, then to find a path cover without vicious circuits, we simply build a maximum collection of non-intersecting paths.

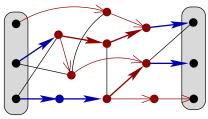
• Use a modified version of an augmenting path algorithm (e.g. Ford-Fulkerson):



- Time required to find a single augmenting path: O(m)
- Time required to find a maximum-size family of paths: O(km)
- By uniqueness: if paths don't cover all vertices, there is no flow.

If (G, I, O) has a flow, then to find a path cover without vicious circuits, we simply build a maximum collection of non-intersecting paths.

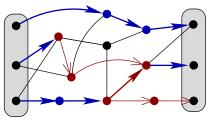
• Use a modified version of an augmenting path algorithm (e.g. Ford-Fulkerson):



- Time required to find a single augmenting path: O(m)
- Time required to find a maximum-size family of paths: O(km)
- By uniqueness: if paths don't cover all vertices, there is no flow.

If (G, I, O) has a flow, then to find a path cover without vicious circuits, we simply build a maximum collection of non-intersecting paths.

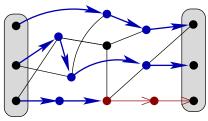
• Use a modified version of an augmenting path algorithm (e.g. Ford-Fulkerson):



- Time required to find a single augmenting path: O(m)
- Time required to find a maximum-size family of paths: O(km)
- By uniqueness: if paths don't cover all vertices, there is no flow.

If (G, I, O) has a flow, then to find a path cover without vicious circuits, we simply build a maximum collection of non-intersecting paths.

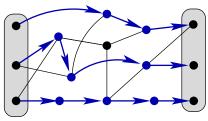
• Use a modified version of an augmenting path algorithm (e.g. Ford-Fulkerson):



- Time required to find a single augmenting path: O(m)
- Time required to find a maximum-size family of paths: O(km)
- By uniqueness: if paths don't cover all vertices, there is no flow.

If (G, I, O) has a flow, then to find a path cover without vicious circuits, we simply build a maximum collection of non-intersecting paths.

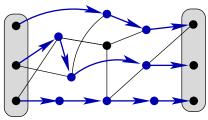
• Use a modified version of an augmenting path algorithm (e.g. Ford-Fulkerson):



- Time required to find a single augmenting path: O(m)
- Time required to find a maximum-size family of paths: O(km)
- By uniqueness: if paths don't cover all vertices, there is no flow.

If (G, I, O) has a flow, then to find a path cover without vicious circuits, we simply build a maximum collection of non-intersecting paths.

• Use a modified version of an augmenting path algorithm (e.g. Ford-Fulkerson):

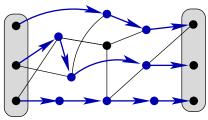


- Time required to find a single augmenting path: O(m)
- Time required to find a maximum-size family of paths: O(km)
- By uniqueness: if paths don't cover all vertices, there is no flow.

(where m = |E|)

If (G, I, O) has a flow, then to find a path cover without vicious circuits, we simply build a maximum collection of non-intersecting paths.

• Use a modified version of an augmenting path algorithm (e.g. Ford-Fulkerson):

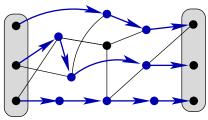


- Time required to find a single augmenting path: O(m)
- Time required to find a maximum-size family of paths: O(km)
- By uniqueness: if paths don't cover all vertices, there is no flow.

(where m = |E| and k = |O|)

If (G, I, O) has a flow, then to find a path cover without vicious circuits, we simply build a maximum collection of non-intersecting paths.

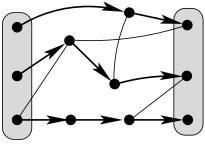
• Use a modified version of an augmenting path algorithm (e.g. Ford-Fulkerson):



- Time required to find a single augmenting path: O(m)
- Time required to find a maximum-size family of paths: O(km)
- By uniqueness: if paths don't cover all vertices, there is no flow.

(where m = |E| and k = |O|)

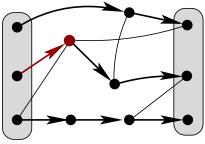
- If (G, I, O) has a flow, then any path-cover \mathcal{P} has no vicious circuits.
 - Use a depth-first search along the influencing walks of *P* to look for vicious circuits.



• By uniqueness: if a vicious circuit is found, there is no flow.

- Can reduce work by storing reachability information at vertices
 - If there are no vicious circuits, this builds a partial order \preccurlyeq
- Time required: O(km) (where m = |E| and k = |O|)

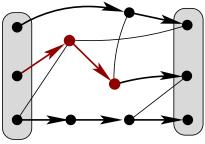
- If (G, I, O) has a flow, then any path-cover \mathcal{P} has no vicious circuits.
 - Use a depth-first search along the influencing walks of *P* to look for vicious circuits.



• By uniqueness: if a vicious circuit is found, there is no flow.

- Can reduce work by storing reachability information at vertices
 - If there are no vicious circuits, this builds a partial order \preccurlyeq
- Time required: O(km) (where m = |E| and k = |O|)

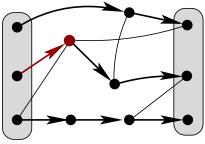
- If (G, I, O) has a flow, then any path-cover \mathcal{P} has no vicious circuits.
 - Use a depth-first search along the influencing walks of *P* to look for vicious circuits.



• By uniqueness: if a vicious circuit is found, there is no flow.

- Can reduce work by storing reachability information at vertices
 - If there are no vicious circuits, this builds a partial order \preccurlyeq
- Time required: O(km) (where m = |E| and k = |O|)

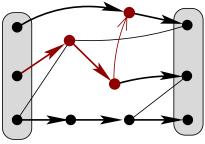
- If (G, I, O) has a flow, then any path-cover \mathcal{P} has no vicious circuits.
 - Use a depth-first search along the influencing walks of *P* to look for vicious circuits.



• By uniqueness: if a vicious circuit is found, there is no flow.

- Can reduce work by storing reachability information at vertices
 - If there are no vicious circuits, this builds a partial order \preccurlyeq
- Time required: O(km) (where m = |E| and k = |O|)

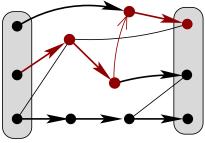
- If (G, I, O) has a flow, then any path-cover \mathcal{P} has no vicious circuits.
 - Use a depth-first search along the influencing walks of *P* to look for vicious circuits.



• By uniqueness: if a vicious circuit is found, there is no flow.

- Can reduce work by storing reachability information at vertices
 - If there are no vicious circuits, this builds a partial order \preccurlyeq
- Time required: O(km) (where m = |E| and k = |O|)

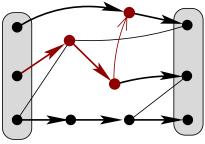
- If (G, I, O) has a flow, then any path-cover \mathcal{P} has no vicious circuits.
 - Use a depth-first search along the influencing walks of *P* to look for vicious circuits.



• By uniqueness: if a vicious circuit is found, there is no flow.

- Can reduce work by storing reachability information at vertices
 - If there are no vicious circuits, this builds a partial order \preccurlyeq
- Time required: O(km) (where m = |E| and k = |O|)

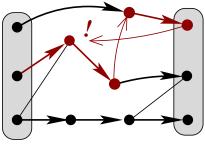
- If (G, I, O) has a flow, then any path-cover \mathcal{P} has no vicious circuits.
 - Use a depth-first search along the influencing walks of *P* to look for vicious circuits.



• By uniqueness: if a vicious circuit is found, there is no flow.

- Can reduce work by storing reachability information at vertices
 - If there are no vicious circuits, this builds a partial order \preccurlyeq
- Time required: O(km) (where m = |E| and k = |O|)

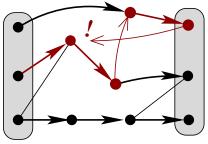
- If (G, I, O) has a flow, then any path-cover \mathcal{P} has no vicious circuits.
 - Use a depth-first search along the influencing walks of *P* to look for vicious circuits.



• By uniqueness: if a vicious circuit is found, there is no flow.

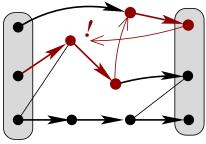
- Can reduce work by storing reachability information at vertices
 - If there are no vicious circuits, this builds a partial order \preccurlyeq
- Time required: O(km) (where m = |E| and k = |O|)

- If (G, I, O) has a flow, then any path-cover \mathcal{P} has no vicious circuits.
 - Use a depth-first search along the influencing walks of *P* to look for vicious circuits.



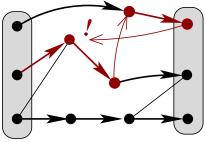
- By uniqueness: if a vicious circuit is found, there is no flow.
- Can reduce work by storing reachability information at vertices
 - If there are no vicious circuits, this builds a partial order \preccurlyeq
- Time required: O(km) (where m = |E| and k = |O|)

- If (G, I, O) has a flow, then any path-cover \mathcal{P} has no vicious circuits.
 - Use a depth-first search along the influencing walks of \mathcal{P} to look for vicious circuits.



- By uniqueness: if a vicious circuit is found, there is no flow.
- Can reduce work by storing reachability information at vertices
 - If there are no vicious circuits, this builds a partial order \preccurlyeq
- Time required: O(km) (where m = |E| and k = |O|)

- If (G, I, O) has a flow, then any path-cover \mathcal{P} has no vicious circuits.
 - Use a depth-first search along the influencing walks of *P* to look for vicious circuits.



- By uniqueness: if a vicious circuit is found, there is no flow.
- Can reduce work by storing reachability information at vertices
 - If there are no vicious circuits, this builds a partial order
- Time required: O(km) (where m = |E| and k = |O|)

Summary

- Flows help describe how information "flows" in the one-way measurement model.
- Finding a flow for a given geometry (*G*, *I*, *O*) seems a natural sub-problem for finding *phase map decompositions*.
- Using graph-theoretic techniques, we can efficiently find flows when |I| = |O|.
- Open problems:
 - ► Can we find flows efficiently in cases where |*I*| < |*O*|?
 - Find families of unitaries where we can efficiently find phase-map decompositions!

References

Diestel.



Danos, Kashefi. Determinism in the one-way model. quant-ph/0506062 (2005).

B, Danos, Kashefi. Phase map decompositions for unitaries. quant-ph/0603266 (2006).

Graph Theory. 3rd ed. Springer-Verlag (2005).



Cormen, Leiserson, Rivest, Stein. Introduction to Algorithms, 2nd ed. MIT Press and McGraw-Hill (2001).